PWM - Pulse Width Modulators

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Benoît STEINMANN Software Team Leader imperix • in

Table of Contents

- Output mode parameter
 - Hardware configuration
- <u>Dead-time parameter</u>
- Activate/deactivate parameter

The Pulse Width Modulators (PWM) share the **dead-time generation** and the **activate/deactivate** features, configured through the output mode, deadtime, and activate parameters.

The said PWM blocks are:

- <u>CB-PWM Carrier-based PWM</u>
- SV-PWM Space vector PWM
- <u>SS-PWM Multilevel PWM with Sort-&-Select balancing</u>
- PP-PWM Programmed Patterns PWM
- DO-PWM Direct output PWM
- SB-PWM Sandbox PWM

Output mode parameter

The Pulse Width Modulators have three possible output modes:

- Single: the modulator provides a single PWM signal on the corresponding output which is referred to as a lane (LN).
- Dual (PWM_H + PWM_L): the modulator provides a pair of complementary signals (PWM high and PWM low) with dead time. A pair of complementary signals output is referred to as a **channel (CH)** and is constituted of adjacent

- lanes. The odd lanes are always low-side signals, while even lanes are always high-side.
- Dual (PWM_H + ACTIVE): in this mode, the PWM_L is replaced by the ACTIVE signal. The ACTIVE signal is 'on' if the PWM block is activated and PWM outputs are enabled (see activate parameter below).

Hardware configuration

The PWM lane and channel numbering are as illustrated below.

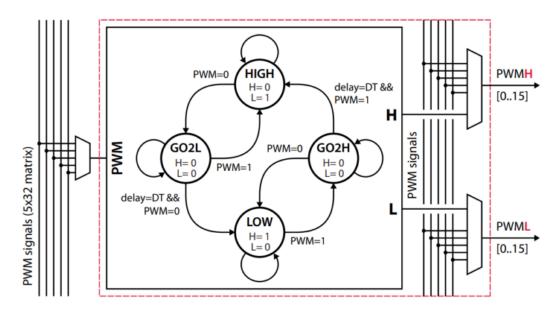
Channel	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	
Lane	0	2	4	6	8	10	12	14	16	18	20	22	24	26	28	30	Н
	1	3	5	7	9	11	13	15	17	19	21	23	25	27	29	31	L
Optical																	
Electrical																	

On a B-Box RCP, the first height channels are output both optically (frontpanel) and electrically (backpannel C and D digital connectors). On a B-Board PRO, all channels are only electrical.

Please refer to the <u>B-Box</u> and the <u>B-Board</u> datasheets for more information.

Dead-time parameter

When the output mode is set as *Dual (PWM_H + PWM_L)* then a dead-time must be configured. The following figure taken from the <u>B-Box datasheet</u> shows the finite-state used to generate the complementary signals with dead-time.



Activate/deactivate parameter

Two conditions must be met for a signal to be outputted on a PWM output:

- The PWM outputs must be **enabled**. This condition is global to the system and can be controlled either from the Cockpit software or from the model using the Enable outputs block.
- The PWM outputs must be **activated**. The PWM outputs are activated by default but the user can choose to have an activate input signal to selectively activate or deactivate a PWM lane or channel during run-time.