### DC bus pre-charging techniques

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Gabriel FERNANDEZ

Operations Manager

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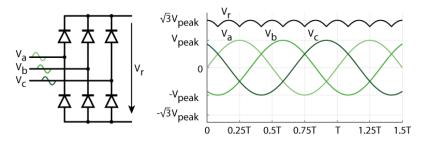
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This application note presents a technique for pre-charging the DC bus of a grid-tie inverter from the AC side. This technique is commonly used in imperix systems. Proper solutions for discharging the power converter is also addressed.

### Why pre-charging an inverter's DC-bus?

Nowadays, Voltage Source Converter (VSCs) are widely used in grid-tied applications. They indeed offer several benefits over Current Source Converters (CSCs), such as reduced filtering requirements, superior efficiency and easier use in weak grid conditions.

However, VSCs impose that the **DC bus voltage is kept higher than the rectified AC voltage**  $V_r$  at all times. This is indeed essential to avoid uncontrollable current flows through the converter diodes. Besides, this condition is also required by the converter's own protection mechanism, which assumes that the blocking of all its PWM signals yields rapidly vanishing currents.



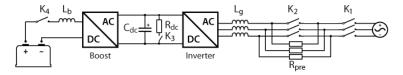
Three phase AC rectifier - rectified voltage

As such, VSCs impose to make sure that the DC bus is appropriately pre-charged before normal operation can be initiated. The corresponding condition is  $V_{DC,min} = \sqrt{3}V_{peak}$ .

Failing to guarantee this condition, before or during operation, very high currents may flow into the converter (only limited by parasitic resistances), **potentially damaging the power semiconductors**.

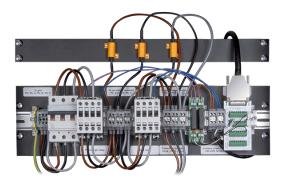
### Pre-charge circuit description

In order to appropriately raise the DC bus voltage before the operation, a pre-charge circuit can be introduced between the converter and the grid, made of a three-phase set of resistors. These resistors can be later bypassed during normal operation, thanks to a software-controlled relay (K2). The figure below shows the corresponding circuit.



AC pre-charge circuit for a 3-phase inverter

One way of implementing that AC pre-charge circuit is by using imperix's handy <u>Grid connection panel</u>. It includes the three current-limiting resistors and the two relays (controllable from a <u>B-Box</u> controller), as well as an additional circuit breaker.



#### Principle of operation

#### Pre-charge of the inverter DC-bus

When the converter is not switching and that its DC bus is not charged, all contactors are open. This corresponds to the standby situation.

To pre-charge the DC bus, the first step is to close the contactor  $K_1$ : then, the converter is connected to the AC grid through resistors, which limit the current flowing from the grid to the DC bus, through the diodes of the inverter. The maximal current flowing into the DC bus capacitor can be expressed as:

$$I_{max} = rac{\sqrt{3}V_{peak}}{2R_{pre}}$$

The second step consists in closing the contactor  $K_2$ . Then, the converter is closely tied to the grid, and operate normally. The precharge resistors are indeed short-circuited and haven't any impact on the operation of the converter.

## Discharge of the inverter DC-bus

For the discharge, all contactors must be opened. Then, a third contactor connected to a resistive load on the DC bus can be closed. The maximum current flowing from the capacitor(s) into the resistance can be expressed as:

$$I_{max} = V_{dc}/R_{dc}$$

The corresponding discharge time can be expressed as:

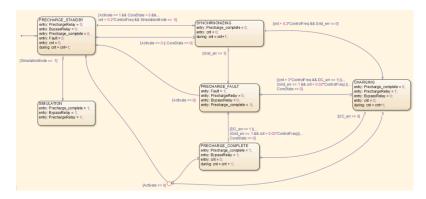
$$t_{dis} = 3 \cdot au = 3 \cdot R_{dc} \cdot C_{dc}$$

Another option consists in re-activating the converter after all contactors are open in order to generate sufficient switching losses so that the discharge of the DC bus is accelerated.

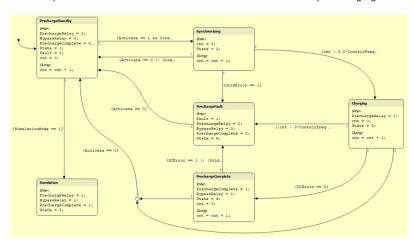
### State machine implementation

As already explained, the order of opening/closing contactors is absolutely essential to avoid potentially damaging current flows. It is also important to take into account the time that each contactor requires for its operation.

For this purpose, the implementation of a state machine is recommended. This also facilitates the grid connection/disconnection procedures, thanks to automated mechanisms. The following shows the implementation of a state machine in C++, Simulink, and PLECS. The grid-tied inverter of the <u>AN006</u> uses that state machine to automate the pre-charge and grid connection processes.



Implementation of a state machine in Simulink for DC-bus pre-charging



Implementation of a state machine in PLECS for DC-bus pre-charging

### C or C++ implementation of a DC-bus pre-charge

```
void User_RunPrechargeFSM()
{
         \ ^{*} This state machine controls the precharge of the DC bus.
         * The user can switch the input "activate" between 1 and 0 to respectively start/stop the precharge.
         * The state machine waits at least 250ms between the "CHARGING" and "CLOSING_BYPASS_RELAY" states.
         * It also waits 200ms between the "CLOSING_BYPASS_RELAY" and "READY_TO_OPERATE" states, because the bypas
         st The output "Ready" indicates that the bus is precharged and the converter is ready to operate.
         * If a fault occurs (CoreState is 0), the state machine goes in "DISCHARGING" state and opens all the rel
         * In simulation, the state machine goes in "SIMULATION" state, to avoid the simulation of the whole prech
        */
        switch (Next_state_precharge){
        // Init
        case PRECHARGE_INIT:
                State precharge = PRECHARGE INIT;
                Next_state_precharge = PRECHARGE_STANDBY;
        // The converter is disconnected from the grid and is in standby, all the relays are open
        case PRECHARGE_STANDBY:
                if (State_precharge != Next_state_precharge)
                        Log_SendMsg(0, NULL, 0);
                State_precharge = Next_state_precharge;
                precharge_relay = 0;
                bypass_relay = 0;
                Precharge_ready = false;
                Precharge_fault = false;
                if (State_precharge != Next_state_precharge)
                        precharge_cnt = 0;
                else
                        precharge_cnt++;
                if (activate == 1 && core_state > 0 && precharge_cnt > 0.2*SW_FREQ)
                {
                        Next_state_precharge = SYNCHRONIZING;
                }
                break:
```

```
// The converter is synchronizing to the grid
case SYNCHRONIZING:
        if (State_precharge != Next_state_precharge)
        {
                Log_SendMsg(1, NULL, 0);
                precharge_cnt = 0;
        }
        else
        {
                precharge_cnt++;
        State_precharge = Next_state_precharge;
        Precharge_ready = false;
        Precharge_fault = false;
        precharge_relay = 0;
        bypass_relay = 0;
        if (precharge cnt > 0.2*SW_FREQ && !err_No_GridSync && !err_No_Grid && core_state != 0)
        {
                Next state precharge = CHARGING;
        else if(activate == 0 || core_state == 0)
        {
                Next_state_precharge = PRECHARGE_STANDBY;
        else if(err_No_GridSync || err_No_Grid)
        {
                Next state precharge = PRECHARGE FAULT;
        }
        break:
// The DC bus of the converter is being charged from the grid (precharge relay closed)
case CHARGING:
        if (State_precharge != Next_state_precharge)
        {
                Log_SendMsg(2, NULL, 0);
                precharge_cnt = 0;
        else
        {
                precharge_cnt++;
        State_precharge = Next_state_precharge;
        Precharge_ready = false;
        Precharge_fault = false;
        precharge_relay = 1;
        bypass_relay = 0;
        if (!err_Vpv_low && !err_Vpv_high && !err_Vdc_low && !err_Vdc_high)
        {
                Next_state_precharge = PRECHARGE_COMPLETE;
        }
        else if ((precharge_cnt > 3*SW_FREQ && (err_Vpv_low || err_Vpv_high || err_Vdc_low || err_Vdc_high
        {
                Next_state_precharge = PRECHARGE_FAULT;
        else if (activate == 0)
        {
                Next_state_precharge = PRECHARGE_STANDBY;
        }
        break;
// The DC bus is precharged and the converter is fully connected to the grid (bypass relay closed)
case PRECHARGE COMPLETE:
        if (State_precharge != Next_state_precharge)
                Log_SendMsg(3, NULL, 0);
        State_precharge = Next_state_precharge;
        precharge_relay = 1;
        bypass_relay = 1;
        Precharge_ready = true;
        Precharge_fault = false;
        if (err_Vpv_low || err_Vpv_high || err_Vdc_low || err_Vdc_high || (precharge_cnt > 0.02*SW_FREQ &&
        {
```

```
Next_state_precharge = PRECHARGE_FAULT;
                else if(activate == 0)
                {
                         Next_state_precharge = PRECHARGE_STANDBY;
                }
                break;
        // A fault occurred during the precharge procedure, all the relays are open
        case PRECHARGE_FAULT:
                if (State_precharge != Next_state_precharge)
                         Log_SendMsg(4, NULL, 0);
                State_precharge = Next_state_precharge;
                precharge_relay = 0;
                bypass_relay = 0;
                Precharge_ready = false;
Precharge_fault = true;
                if(activate == 0)
                         Next_state_precharge = PRECHARGE_STANDBY;
                }
                break;
        }
        state_precharge_uint = (unsigned int) State_precharge;
}Code language: C++ (cpp)
```

# Other applications

The same DC-bus precharge technique can be used for other grid-connected voltage-source inverter topologies. This also includes multi-level topologies such as <u>cascaded H-bridges (TN165)</u>, which can be used in higher voltage applications such as <u>solid-state transformers (AN015)</u>.